## Code No: D7502 JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY HYDERABAD M.Tech II - Semester Examinations, March 2011 ADAPTIVE CONTROL THEORY (CONTROL SYSTEMS) Time: 3hours Max. Marks: 60

## Answer any five questions All questions carry equal marks

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1.	What are the different types of adaptive schemes? Explain in detail.	[12]	
2.	Consider a system described by a model.	r	
	dy/dt = -ay+bu,		
	Where u is the control variable and y is the measured output. Assume	that we want to	
	obtain a closed loop system described by $dy_m/dt = -a_m y_m + b_m u_c$ $u(t) = \theta_1 u_c$	ed loop system described by $dy_m/dt = -a_m y_m + b_m u_c$ $u(t) = \theta_1 u_c(t) - \theta_2 y(t)$ .	
	Design a Model reference adaptive system (MRAS) using MIT rule.	[12]	
3.	How to design a MRAS using		
	a) Hyper stability approach?		
	b) Narendra's error model approach?	[6+6]	
4.	xplain the design procedure of Self tuning regulator using pole placement method.		
		[12]	
5.	Explain the hybrid predictor design and hybrid self tuning algorithm.	[12]	
6.	Explain stochastic adaptive control and dual control.	[12]	

- 7. Explain the adaptive control systems application in the following areas:
  - a) Power systems.
    b) Electric drives. [6+6]
    Write short notes on:
  - a) Recursive parameter estimation.

8.

b) Direct and indirect MRAS. [6+6]

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